

Thursday, February 22, 2001
1:00 p.m. — 2:20 p.m.
161 Everitt Laboratory

Instructions:

There are **four problems** on this examination worth a total of 125 points.

One page of notes allowed. No other notes, books, tables of integrals, and calculators/personal computers permitted.

Show all your work in the exam booklet provided. Answers without appropriate justification will receive no credit.

Notation and (possibly) useful formulas

$\Phi(x)$ = cumulative probability distribution function for zero-mean unit-variance (i.e., standard) Gaussian random variable

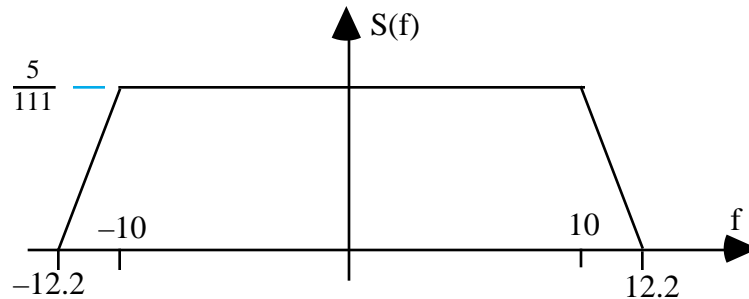
$$Q(x) = 1 - \Phi(x)$$

$P_{e,i}$ = probability of error given that signal $s_i(t)$ was transmitted

AWGN denotes additive white Gaussian noise with (two-sided) power spectral density $N_0/2$. This random process is independent of the choice of transmitted signal. The mean of this process is 0.

$\text{rect}(t) = \begin{cases} 1 & \text{if } -1/2 \leq t \leq 1/2, \\ 0 & \text{otherwise.} \end{cases}$ $X(t) \rightarrow X(-f)$ $x^*(t) \rightarrow X^*(-f)$ $x(t-t_0) \rightarrow X(f) \cdot \exp(-j2\pi f t_0)$ $x(t) \cdot \cos(2\pi f_0 t) \rightarrow (1/2)[X(f+f_0) + X(f-f_0)]$ $\frac{d}{dt} x(t) \rightarrow (j2\pi f) \cdot X(f)$ $x * y = \int_{-\infty}^{\infty} x(\tau) \cdot y(t-\tau) d\tau$ $\int_{-\infty}^{\infty} X(f) \cdot Y(f-f) df$ $\int_{-\infty}^{\infty} x(t) ^2 dt = \int_{-\infty}^{\infty} X(f) ^2 df$ $R_{X,Y}(\tau) = \int_{-\infty}^{\infty} x(t+\tau) \cdot y^*(t) dt$ $\text{rect}(t/T) \rightarrow T \cdot \text{sinc}(fT)$ <p>where $\text{sinc}(z) = \frac{\sin z}{z}$ is the <i>sinc function</i></p>	$p_T(t) = \begin{cases} 1, & \text{if } 0 \leq t < T, \\ 0, & \text{otherwise.} \end{cases}$ $x(t) \rightarrow \int_{-\infty}^{\infty} X(f) \cdot e^{j2\pi f t} df$ $x^*(-t) \rightarrow X^*(f)$ $x(t) \cdot \exp(j2\pi f_0 t) \rightarrow X(f-f_0)$ $x(t) \cdot \sin(2\pi f_0 t) \rightarrow (j/2)[X(f+f_0) - X(f-f_0)]$ $\int_{-\infty}^{\infty} x(t) \cdot y^*(t) dt = \int_{-\infty}^{\infty} X(f) \cdot Y^*(f) df$ $X(f) \cdot Y(f) \rightarrow \int_{-\infty}^{\infty} x(t) \cdot y(t) dt$ $X(f) \cdot Y(f) = \int_{-\infty}^{\infty} X(f) \cdot Y^*(f) df$ $W \cdot \text{sinc}(Wt) \rightarrow \text{rect}(f/W)$
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1. (20 points) A signal $s(t)$ has Fourier transform $S(f)$ as sketched below. Find $s(t)$. In order to receive full credit, you must specify $s(t)$ for all t , $-\infty < t < \infty$.



2. (20 points) The input to a linear time-invariant system with impulse response
- $$h(t) = \begin{cases} \exp(-t), & 0 \leq t < \infty \\ 0, & t < 0 \end{cases}$$

is a zero-mean WSS Gaussian random process $\{\mathbf{X}(t) : -\infty < t < \infty\}$ with autocorrelation function

$$R_{\mathbf{X}}(\tau) = \exp(-2|\tau|), \quad -\infty < \tau < \infty.$$

Let $\{\mathbf{Y}(t) : -\infty < t < \infty\}$ denote the output process. What is the variance of $\mathbf{Y}(1)$?

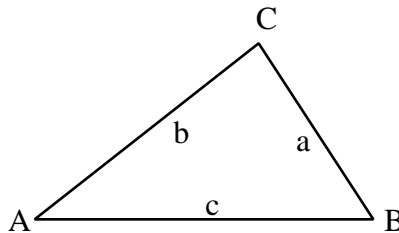
3. (45 points) Consider a binary baseband digital communication system operating on an AWGN channel with transmitted signals given by

$$s_0(t) = A \cdot p_T(t) \quad \text{and} \quad s_1(t) = A \cdot (t/T) \cdot p_T(t).$$

We consider the error probability performance for three receivers for this signal set.

- (a) Suppose that the receiver consists of a linear filter with impulse response $h(t) = A \cdot p_T(t)$, a sampler at time T , and the minimax threshold is used. Note that $h(t) = s_0(t)$. What is the minimax error probability P_e ? Call this number $P_{e,\text{part(a)}}$.
- (b) Now suppose that the receiver filter is $h(t) = A \cdot (t/T) \cdot p_T(t)$, while the sampling time remains T as before, and the appropriate minimax threshold is used. Note also that $h(t) = s_1(t)$. What is the value of the minimax error probability P_e ? Call this number $P_{e,\text{part(b)}}$.
- (c) What is the optimum minimax error probability achievable with signals $s_0(t)$ and $s_1(t)$? You are not asked to compute the impulse response of the matched filter, or the minimax threshold, or ... for this receiver. I just want to know P_e . Call this number $P_{e,\text{part(c)}}$.
- (d) Compare probabilities $P_{e,\text{part(a)}}$, $P_{e,\text{part(b)}}$ and $P_{e,\text{part(c)}}$ to determine which is the smallest.
- (e) Do ONE of the following three parts as appropriate:
- (i) If you found that $P_{e,\text{part(a)}} < P_{e,\text{part(c)}}$ **or** $P_{e,\text{part(b)}} < P_{e,\text{part(c)}}$ (**or both!!**) explain why the matched filter receiver of part (c), which is supposed to be optimum, has poorer performance than the receiver of part (a) or the receiver of part (b).
- (ii) If you found that $P_{e,\text{part(a)}} > P_{e,\text{part(c)}}$ **and** $P_{e,\text{part(b)}} = P_{e,\text{part(c)}}$, explain why a receiver with filter $h(t) = s_1(t)$ has better performance than a receiver with filter $h(t) = s_0(t)$.
- (iii) If you found that $P_{e,\text{part(a)}} > P_{e,\text{part(c)}}$ **and** $P_{e,\text{part(b)}} > P_{e,\text{part(c)}}$, draw a neat sketch of the signals $s_0(t)$ and $s_1(t)$, and the impulse response of the matched filter of the receiver of part (c), all on the same axes (for ease of comparison).

4. (40 points) Let $s_0(t)$ and $s_1(t)$ denote two signals of finite energies E_0 and E_1 respectively.
- (a) What is the optimum minimax error probability achievable with these signals in an AWGN channel?
- Now suppose that $s_0(t)$ and $s_1(t)$ are represented as points $\mathbf{s}_0 = (c_{00}, c_{01})$ and $\mathbf{s}_1 = (c_{10}, c_{11})$ in a signal space with orthonormal basis functions $\{\phi_0(t), \phi_1(t)\}$. Do **NOT** assume that $\phi_0(t)$ and $\phi_1(t)$ were obtained via a Gram-Schmidt orthonormalization procedure, that is, do **not** assume that $s_0(t) = c_{00} \phi_0(t)$ and thus $c_{01} = 0$; none of $c_{00}, c_{01}, c_{10},$ and c_{11} is necessarily equal to 0.
- (b) Let d_{01} denote the distance between \mathbf{s}_0 and \mathbf{s}_1 . Express the optimum minimax error probability in terms of d_{01}, N_0 (and components $c_{00}, c_{01}, c_{10}, c_{11}$ of \mathbf{s}_0 and \mathbf{s}_1 if needed).
- (c) Let d_0 and d_1 denote the distances of \mathbf{s}_0 and \mathbf{s}_1 respectively from the origin $\mathbf{0} = (0,0)$. Let θ denote the angle between the straight line through \mathbf{s}_0 and $\mathbf{0}$ and the straight line through \mathbf{s}_1 and $\mathbf{0}$. What is $\cos \theta$? Express your answer in two different forms: in terms of d_0 and d_1 (and $c_{00}, c_{01}, c_{10}, c_{11}$ if needed), and in terms of E_0 and E_1 (and $c_{00}, c_{01}, c_{10}, c_{11}$ if needed)
- (d) In a triangle, any side can be expressed in terms of the other two sides and the angle between these other sides. For example, in the triangle ABC shown below,



- $c^2 = a^2 + b^2 - 2 \cdot a \cdot b \cdot \cos C$, and similarly for sides a and b . Use this result to derive a relationship between $d_{01}, d_0,$ and d_1 and thus show that the argument of $Q(\bullet)$ that you obtained in part (b) is the same as the argument of $Q(\bullet)$ that you obtained in part (a).
- (e) What choice(s) of \mathbf{s}_0 and \mathbf{s}_1 will minimize the optimum minimax error probability and what is this minimum value of the optimum minimax error probability? Do not forget that the signals are constrained to have energies E_0 and E_1 respectively. Drawing a sketch will help you think through this problem.
- (f) Let us return to the case of *arbitrary* points \mathbf{s}_0 and \mathbf{s}_1 at distance d_{01} apart, and representing signals $s_0(t)$ and $s_1(t)$ of energies E_0 and E_1 respectively. Bear in mind that \mathbf{s}_0 and \mathbf{s}_1 are not necessarily in the locations that you described in your answer to part (e).
- Consider a modified receiver that works as follows. If the received vector $\mathbf{r} = (r_0, r_1)$ is within distance $d_{01}/2$ of one of the signal points \mathbf{s}_0 and \mathbf{s}_1 , the receiver decides that that signal was transmitted. If neither signal point is within distance $d_{01}/2$ of \mathbf{r} , the receiver asks the transmitter to re-send the signal. For $i = 0, 1$, let \mathcal{R}_i denote the set of all \mathbf{r} for which the decision is that \mathbf{s}_i was transmitted, and note that \mathcal{R}_0 and \mathcal{R}_1 are disjoint sets but their union is **not** the entire plane.
- (i) Draw a sketch illustrating the decision regions \mathcal{R}_0 and \mathcal{R}_1 .
- (ii) Show that $P(\mathbf{r} \in \mathcal{R}_0 \mid s_0(t) \text{ transmitted})$, the probability that the receiver correctly decides that $s_0(t)$ was transmitted when $s_0(t)$ was in fact transmitted, equals $1 - \exp(-d_{01}^2/4N_0)$.