

Instructions:

There are **four problems** on this examination.

One page of notes allowed. No other notes, books, tables of integrals, and calculators/personal computers permitted.

Show all your work in the exam booklet provided. Answers without appropriate justification will receive no credit.

Notation: For $\tau > 0$, $p(t) = \begin{cases} 1 & \text{if } 0 < t < \tau \\ 0 & \text{otherwise.} \end{cases}$

$\Phi(x) =$ cumulative probability distribution function for standard (zero-mean unit-variance) Gaussian random variable

$Q(x) = 1 - \Phi(x)$

$P_{e,i} =$ probability of error given that signal $s_i(t)$ was transmitted

AWGN denotes additive (zero-mean) white Gaussian noise with power spectral density $N_0/2$. This random process is independent of the choice of transmitted signal.

Some more-or-less useful facts:

$$\begin{aligned} 2 \cdot \cos^2(x) &= 1 + \cos(2x) & 2 \cdot \sin^2(x) &= 1 - \cos(2x) \\ \cos(x+y) &= \cos(x)\cos(y) - \sin(x)\sin(y) & \sin(x+y) &= \sin(x)\cos(y) + \cos(x)\sin(y) \\ \text{rect}(t/T) &= T \cdot \text{sinc}(fT) & \text{and} & \quad W \cdot \text{sinc}(Wt) = \text{rect}(f/W) \text{ where } \text{sinc}(x) = \frac{\sin(x)}{x} \end{aligned}$$

$$\cos(2f_c t) = \frac{1}{2} [\cos((f+f_c)t) + \cos((f-f_c)t)] \quad \sin(2f_c t) = \frac{1}{2j} [\cos((f+f_c)t) - \cos((f-f_c)t)]$$

Rayleigh density function: $f(r) = \frac{r}{2} \cdot \exp\left(-\frac{r^2}{2}\right), r > 0$

Rician density function: $f(r) = \frac{r}{2} \cdot I_0\left(\frac{rA}{2}\right) \cdot \exp\left(-\frac{r^2+A^2}{2}\right), r > 0,$

$$\text{where } I_0(x) = \frac{1}{2\pi} \int_0^{2\pi} \exp(x \cdot \cos(\theta)) d\theta$$

1. **(35 points)** Let $\{b_k\}$ denote a sequence of independent data bits each likely to take on values 0 and 1 with equal probability. This sequence is to be transmitted over an AWGN channel at the (slow!) data rate of 0.5 bit/second using energy E per bit.

Consider first a binary communication system using the signal

$$\sqrt{E} \cdot p_1(t - 2k - b_k)$$

- (a) Sketch the four possible signals that can be observed in the time interval $[0, 4)$.

Consider next a 4-ary communication system using the signal

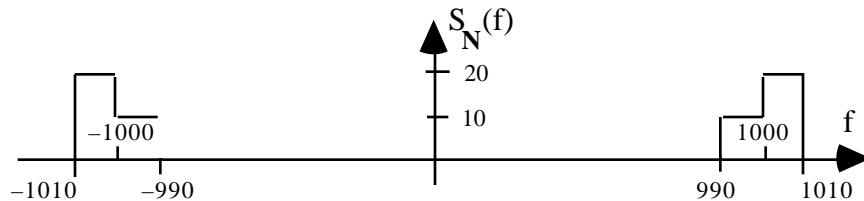
$$\sqrt{2E} \cdot p_1(t - 4k - b_{2k} - 2b_{2k+1})$$

- (b) Sketch the four possible signals that can be observed in the time interval $[0, 4)$.
- (c) **State** the bit error probabilities of these two communication systems. Which has larger bit error probability?
- (d) Compare the bandwidth required to implement these communication systems. Which has a larger bandwidth?
- (e) Write an expression similar to the ones above for the transmitted signal in a communication system using 8-ary orthogonal signaling with (positive) rectangular pulses. The data rate must be 1/2 bit/second and the energy per bit must be E (just as with the two systems discussed above.) What is the bandwidth required for this signal set? What is the peak power requirement compared to the binary and 4-ary systems described above?

2. (35 points) A zero-mean wide-sense-stationary narrowband random process $\{N(t)\}$ has power spectral density $S_N(f)$ as shown below (not to scale). The quadrature components of $\{N(t)\}$ with respect to the center frequency $f_c = 1$ kHz are given by

$$N(t) = X(t) \cdot \cos(2(1000)t) - Y(t) \cdot \sin(2(1000)t)$$

where $\{X(t)\}$ and $\{Y(t)\}$ are low-pass processes.



- (a) Find the autocorrelation function $R_N(t)$ of the process by computing the inverse Fourier transform of $S_N(f)$.
- (b) Find the power spectral density $S_X(f)$ of the random process $\{X(t)\}$.
- (c) Find the autocorrelation function $R_X(t)$ of the random process $\{X(t)\}$ by computing the inverse Fourier transform of $S_X(f)$.
- (d) Find the autocorrelation function $R_X(t)$ of the random process $\{X(t)\}$ via the integral formula $R_X(t) = 2 \int_0^\infty S_N(f) \cdot \cos(2(f-1000)t) df$ and compare to your result in part (c).

3. (30 points) For $0 \leq t < 2T$, a QPSK signal is given by

$$\sqrt{E/T} \cdot [(-1)^{a_0} \cdot \cos(2 f_c t) - (-1)^{a_1} \cdot \sin(2 f_c t)].$$

An optimum coherent receiver for this signal (in an AWGN channel) uses local reference carriers $2 \cdot \cos(2 f_c t)$ and $-2 \cdot \sin(2 f_c t)$ that are derived from a single VCO source via phase delays (as described in class and in homework.)

- (a) **State** the bit error probabilities in the I and Q branches of the optimum receiver in terms of one or more of the parameters E , T , f_c , and N_0 . You are **not asked** to provide a detailed analysis of how you obtained this result.
- (b) Now suppose that due to phase-tracking errors in the PLL and component imperfections in the phase-delay circuitry, the local reference carriers are actually $2 \cdot \cos(2 f_c t + \theta)$ and $-2 \cdot \sin(2 f_c t + \theta)$ where θ and θ' are small compared to $\pi/2$. What are the error probabilities in the I and Q branches if $a_0 = 0$ and $a_1 = 1$?

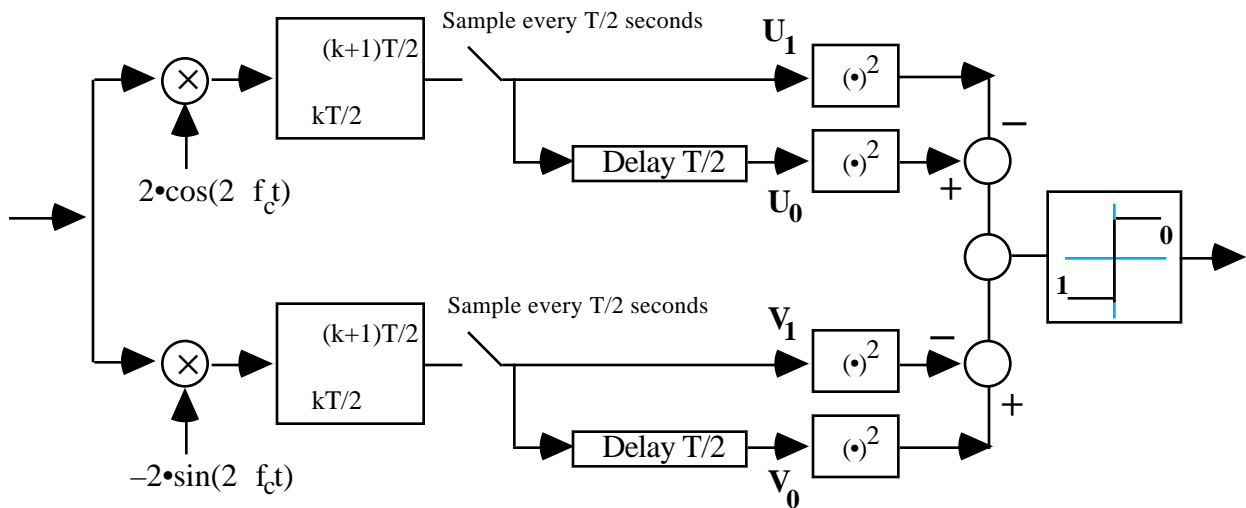
4. (25 points) A PPM system operating on an AWGN channel uses signals

$$s_0(t) = \sqrt{2}A \cdot p_{T/2}(t) \cdot \cos(2\pi f_c t)$$

$$s_1(t) = \sqrt{2}A \cdot p_{T/2}(t - T/2) \cdot \cos(2\pi f_c t)$$

where $f_c T$ is a large even integer and θ is unknown.

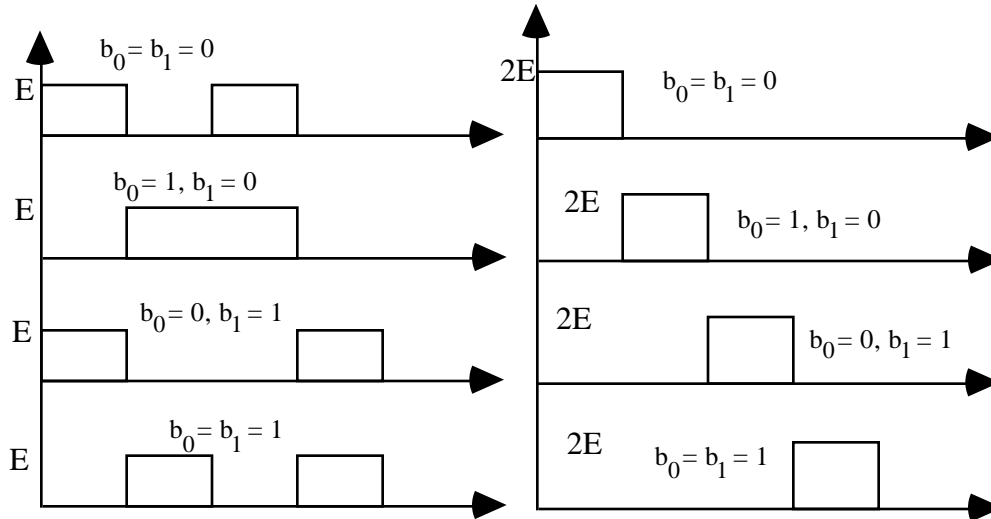
A noncoherent correlation receiver for this signal set is shown below where the integrator outputs are sampled at integer multiples of $T/2$. The diagram indicates the state of affairs at time T . **Note that the integrator is dumped (that is, its output is reset to 0 and the integration is restarted) at the end of each $T/2$ second period. The decision is made once every T seconds.**



As shown, U_0 and V_0 denote the sample values at time $t = T/2$ and U_1 and V_1 denote the sample values at time $t = T$. The receiver computes $\{(U_0)^2 + (V_0)^2\} - \{(U_1)^2 + (V_1)^2\}$ and decides that $s_0(t)$ was transmitted if this quantity is positive.

- Explain why $s_0(t)$ and $s_1(t)$ are orthogonal over the interval $[0, T]$ even though they are at the same carrier frequency f_c and have the same phase.
- Compute the means and variances of U_0 , V_0 , U_1 , and V_1 conditioned on $s_0(t)$ being transmitted and $\theta = \pi/4$.
- Use the results of part (b) to **state** the error probability of this receiver in terms of one or more of the parameters A , T , f_c , and N_0 . You are **not asked** to provide a derivation of your answer via integration of pdfs etc.

1.(a), (b) The four possible signals are as shown below.



(c) The first system uses *binary orthogonal signaling* with energy E per bit and hence its bit error probability is $Q(\sqrt{E/N_0})$. The second system uses *4-ary orthogonal signaling* with symbol energy $2E$ per symbol, and hence, according to a formula discussed in class, its bit error probability is given by

$$\left[\frac{4}{2 \cdot (4-1)} \right] \cdot P_{e,s} = (2/3) \cdot P_{e,s} = (2/3) \cdot \int_0^1 \int_0^1 (x - \sqrt{4E/N_0}) dx \cdot \int_0^1 (x - \sqrt{4E/N_0}) dx$$

$= Q(\sqrt{2E/N_0})$ where we got the upper bound by replacing (x) with 1 and then interpreted the integral as $P\{X < Y\}$ where X and Y are independent $N(\sqrt{4E/N_0}, 1)$ and $N(0, 1)$ random variables. Since $Q(\sqrt{2E/N_0}) \ll Q(\sqrt{E/N_0})$, we can be sure that the first system has larger bit error probability for large E/N_0 . However, for *very small* E/N_0 , binary orthogonal signaling *can* achieve a smaller bit error rate.

(d) From the figure above, it seems reasonable to assume that both systems use the same bandwidth. Note that the Landau-Pollak theorem states that there are roughly $2W_0T_0$ orthogonal signals of limited duration T_0 and roughly limited bandwidth W_0 . The first system needs 2 orthogonal signals of duration 2 seconds while the second needs 4 signals of duration 4 seconds. Thus, both systems could be implemented in the same bandwidth of $W_0 = 1/2$ Hz.

(e) The 8-ary system uses orthogonal signaling to transmit 3 bits. Hence, the symbol energy is $3E$ per symbol, and the "symbol duration" is 6 seconds. Since 8 PPM pulses must fit into 6 seconds, the pulse duration must be 0.75 second, and the pulse amplitude must be $2\sqrt{E}$. Thus, the signal is

$$2\sqrt{E} \cdot \sum_{k=0}^7 p_{0.75}(t - 6k - (b_{3k} + 2b_{3k+1} + 4b_{3k+2}) \cdot 0.75)$$

Note that the 8-ary signal set needs 8 orthogonal signals in 6 seconds, so that the bandwidth required is $2/3$ Hz which is larger than $1/2$ Hz! This illustrates the bandwidth expansion required for M -ary orthogonal signaling. Also, the signals (both the 4-ary set as well as the 8-ary set) need more peak power for transmission than binary signaling at the same bit rate. This is a characteristic of PPM signaling.

$$\begin{aligned} 2.(a) \quad R_N(t) &= \int_{-1000}^{1000} S_N(f) \exp(j2\pi ft) df = 2 \int_{990}^{1000} 10 \cos(2\pi ft) df + 2 \int_{1000}^{1010} 20 \cos(2\pi ft) df = 10 \frac{\sin(2\pi \cdot 1000 t)}{t} \Big|_{990}^{1000} + 20 \frac{\sin(2\pi \cdot 1010 t)}{t} \Big|_{1000}^{1010} \\ &= 10 \frac{\sin(2\pi \cdot 1000 t) - \sin(2\pi \cdot 990 t)}{t} + 20 \frac{\sin(2\pi \cdot 1010 t) - \sin(2\pi \cdot 1000 t)}{t} \\ &= 20 [\cos(2\pi \cdot 995 t) + 40 \cos(2\pi \cdot 1005 t)] \frac{\sin(2\pi \cdot 5 t)}{t} = 200 [\cos(2\pi \cdot 995 t) + 2 \cos(2\pi \cdot 1005 t)] \text{sinc}(10t). \end{aligned}$$

Quick check: $R_N(0) = \text{area under } S_N(f) = 600$ according to both our formula and the given picture.

An alternative derivation of the same result uses the inverse transform $W \cdot \text{sinc}(Wt) \leftrightarrow \text{rect}(f/W)$. Note that $S_N(f) = (1/2) \cdot [G(f-995) + G(f+995)] + (1/2) \cdot [2 \cdot G(f-1005) + 2 \cdot G(f+1005)]$ where $G(f) = 20 \cdot \text{rect}(f/10)$ has inverse transform $200 \cdot \text{sinc}(10t)$. Hence $R_N(t) = 200 \cdot [\cos(2 \cdot (995)t) + 2 \cdot \cos(2 \cdot (1005)t)] \cdot \text{sinc}(10t)$ by the modulation theorem.

(b) With $f_c = 1$ kHz, $S_X(f) = \begin{cases} S_N(f-1000) + S_N(f+1000), & |f| < 1000, \\ 0, & \text{otherwise.} \end{cases}$ Thus, $S_X(f) = 30 \cdot \text{rect}(f/20)$.

(c) $R_X(t) \leftrightarrow S_X(f) = 30 \cdot \text{rect}(f/20)$. Since $W \cdot \text{sinc}(Wt) \leftrightarrow \text{rect}(f/W)$, we get that $R_X(t) = 600 \cdot \text{sinc}(20t)$.

(d)
$$R_X(t) = 2 \int_0^{1000} S_N(f) \cos(2 \cdot (f-1000)t) df = 2 \int_{990}^{1000} 10 \cdot \cos(2 \cdot (f-1000)t) df + 2 \int_{1000}^{1010} 20 \cdot \cos(2 \cdot (f-1000)t) df$$

$$= \frac{10 \cdot \sin(2 \cdot (f-1000)t)}{t} \Big|_{990}^{1000} + \frac{20 \cdot \sin(2 \cdot (f-1000)t)}{t} \Big|_{1000}^{1010} = 600 \cdot \text{sinc}(20t) \text{ just as in part (c).}$$

3.(a) The energy in each sinusoid is $(E/T) \cdot (1/2) \cdot 2T = E$. With antipodal signaling and an optimum receiver, the error probability in each branch is thus $Q \sqrt{\frac{2E}{N_0}}$.

(b) Since $a_0 = 0$ and $a_1 = 1$, the received signal is $\sqrt{E/T} \cdot [\cos(2 \cdot f_c t) + \sin(2 \cdot f_c t)]$ and the signal output in the I branch is $\int_0^{2T} \sqrt{E/T} \cdot [\cos(2 \cdot f_c t) + \sin(2 \cdot f_c t)] \cdot 2 \cdot \cos(2 \cdot f_c t) dt = \sqrt{E/T} \cdot 2T \cdot [\cos - \sin]$ where we have used the identities $2 \cdot \cos(A) \cdot \cos(B) = \cos(A+B) + \cos(A-B)$ and $2 \cdot \sin(A) \cdot \cos(B) = \sin(A+B) + \sin(A-B)$ and ignored the double-frequency terms. Note that we would have had $\cos + \sin$ if $a_1 = 0$. Similarly, the Q

branch signal output is $-\int_0^{2T} \sqrt{E/T} \cdot [\cos(2 \cdot f_c t) + \sin(2 \cdot f_c t)] \cdot 2 \cdot \sin(2 \cdot f_c t) dt = -\sqrt{E/T} \cdot 2T \cdot [\sin + \cos]$.

The noise variance in either branch is $(N_0/2) \int_0^{2T} 4 \cdot \cos^2(2 \cdot f_c t) dt = (N_0/2) \int_0^{2T} 4 \cdot \sin^2(2 \cdot f_c t) dt = 2N_0T$.

Hence, the error probabilities are $Q \sqrt{\frac{2E}{N_0}} \cdot [\cos - \sin]$ in the I branch and $Q \sqrt{\frac{2E}{N_0}} \cdot [\cos + \sin]$ in the Q branch.

4.(a) The signals are orthogonal because the baseband signals $p_{T/2}(t)$ and $p_{T/2}(t-T/2)$ have non-overlapping support, i.e. $s_0(t)s_1(t) = 0$ for all t .

(b) Given that s_0 was transmitted and $\theta = \pi/4$, U_0, V_0, U_1 , and V_1 are independent Gaussian random variables with common variance

$$\sigma^2 = \frac{N_0}{2} \int_0^{T/2} 4 \cdot \cos^2(2 \cdot f_c t) dt = \frac{N_0}{2} \int_0^{T/2} 4 \cdot \sin^2(2 \cdot f_c t) dt = \frac{N_0}{2} \int_{T/2}^T 4 \cdot \cos^2(2 \cdot f_c t) dt = \frac{N_0}{2} \int_{T/2}^T 4 \cdot \sin^2(2 \cdot f_c t) dt = \frac{N_0 T}{2}.$$

$E[U_0] = \int_0^{T/2} \sqrt{2A} \cdot \cos(2 \cdot f_c t + \pi/4) \cdot 2 \cdot \cos(2 \cdot f_c t) dt = \sqrt{2A} \cdot (T/2) \cdot \cos(\pi/4)$, $E[U_1] = 0$ (no signal in $(T/2, T)$!!)

$E[V_0] = \int_0^{T/2} \sqrt{2A} \cdot \cos(2 \cdot f_c t + \pi/4) \cdot (-2) \cdot \sin(2 \cdot f_c t) dt = \sqrt{2A} \cdot (T/2) \cdot \sin(\pi/4)$, $E[V_1] = 0$ (no signal in $(T/2, T)$!!)

(c) This is noncoherent demodulation of orthogonal signals, and the error probability is $(1/2) \cdot \exp(-(A_0)^2/4 \cdot \sigma^2)$ where $(A_0)^2 = (E[U_0])^2 + (E[V_0])^2 = 2A^2(T/2)^2 = A^2T^2/2$. Hence, $P_e = (1/2) \cdot \exp(-A^2T/4N_0) = (1/2) \cdot \exp(-E/2N_0)$ since the energy in each pulse of rms amplitude A is $E = A^2(T/2)$.